

**an efficient data structure  
for Must-Alias Analysis**

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**an efficient data structure**  
**for Must-Alias Analysis**

$$\begin{aligned}x &= y \\ y.f &= z\end{aligned}$$

*aliasing expressions refer  
to the same memory*

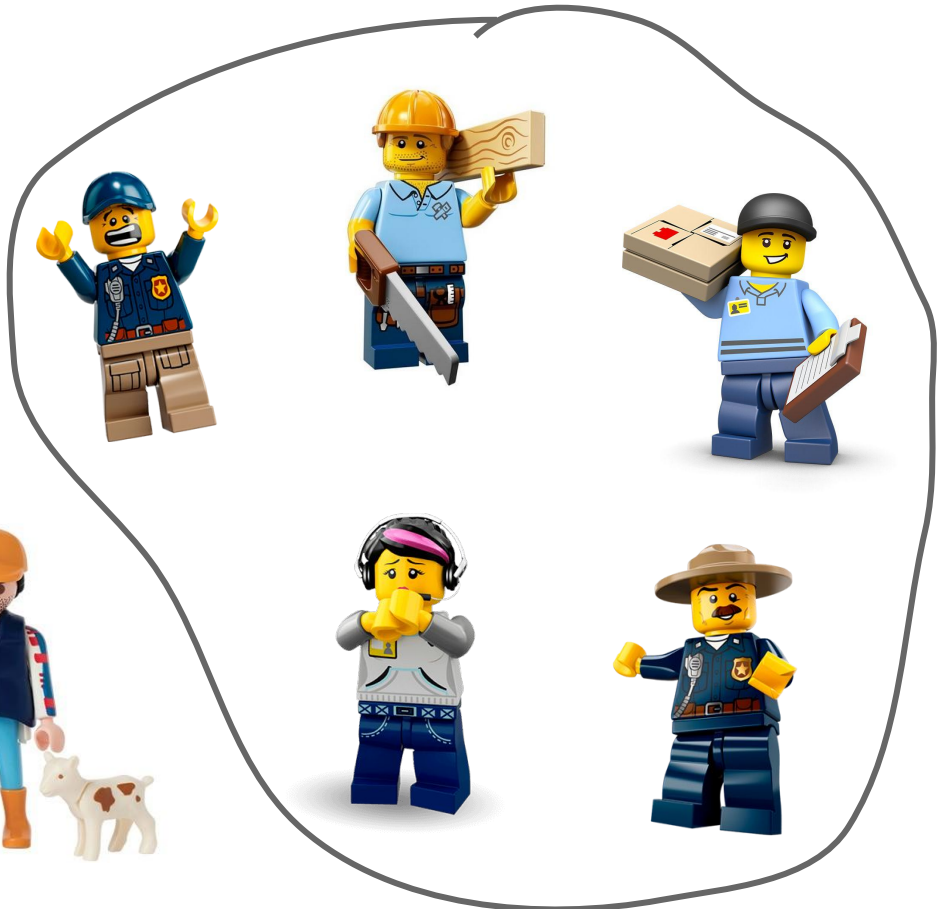
$$\begin{aligned}x &\sim y \\ y.f &\sim z \\ x.f &\sim z\end{aligned}$$

**an efficient data structure**  
**for Must-Alias Analysis**

# Find the LEGO



# Truth



# May (Over)



# Must (under)





**I don't always  
report aliasing...**



**But when I do, I'm  
sure!**

# **Insights for efficiency**

# ***Must-Alias: an Equivalence Relation***

$x \sim y$

$y \sim z$

---

$x \sim z$

# ***Must-Alias: an Equivalence Relation***



**N aliasing elements → N<sup>2</sup> pairs**

x ~ y

y ~ z



x ~ z

# Implicit access path extension



**c fields, k max length**

→  $\Omega(c^k)$  access paths

$$x \sim y$$

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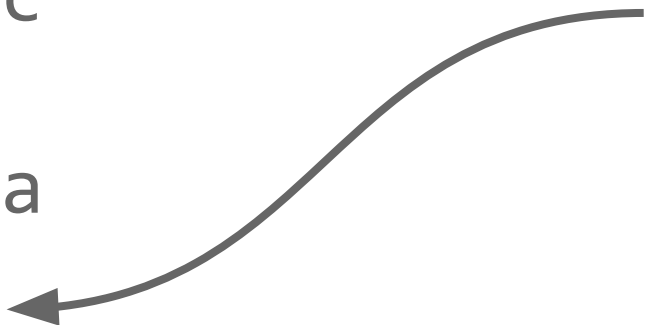
$$x.f \sim y.f$$

$$x.g \sim y.g$$

$$x.g.k \sim y.g.k$$

# **May-Alias is NOT an equivalence relation**

```
x = a  
if (...)  
    y = c  
else  
    y = a
```

$$\begin{array}{l} x \sim a \\ y \sim c \\ y \sim a \\ \hline x \sim y \\ x \ ? \ c \end{array}$$


*how much?*

**an efficient data structure**  
**for Must-Alias Analysis**

*Datalog Naive*  
*(the old)*

**Explicitly represent  
alias pairs**

**Explicitly extend  
access paths  
(max len)**

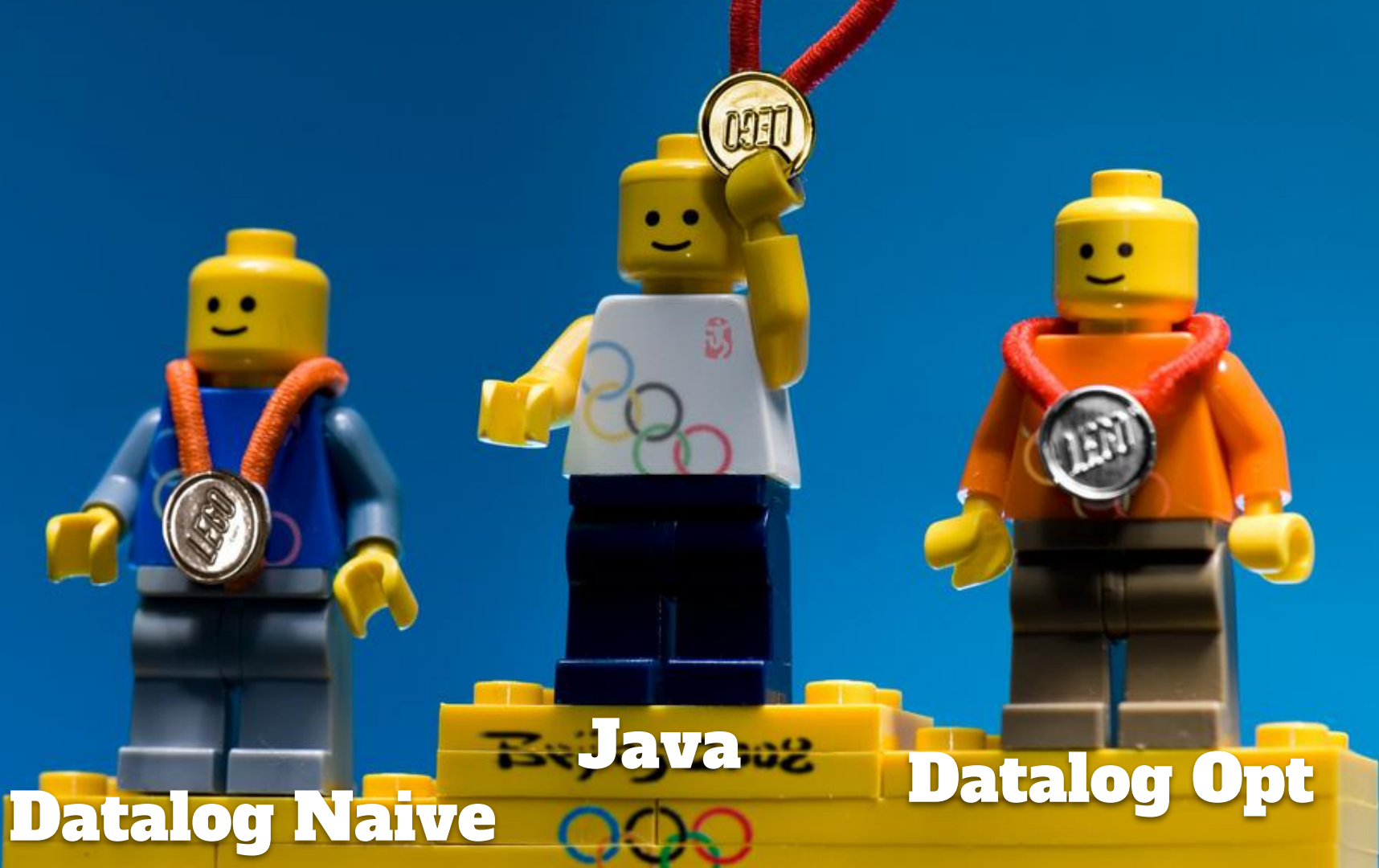
*Java*

**Data structure for implicit  
representation of both points**

*Datalog Opt*

**Simulated in a  
purely  
declarative setup**

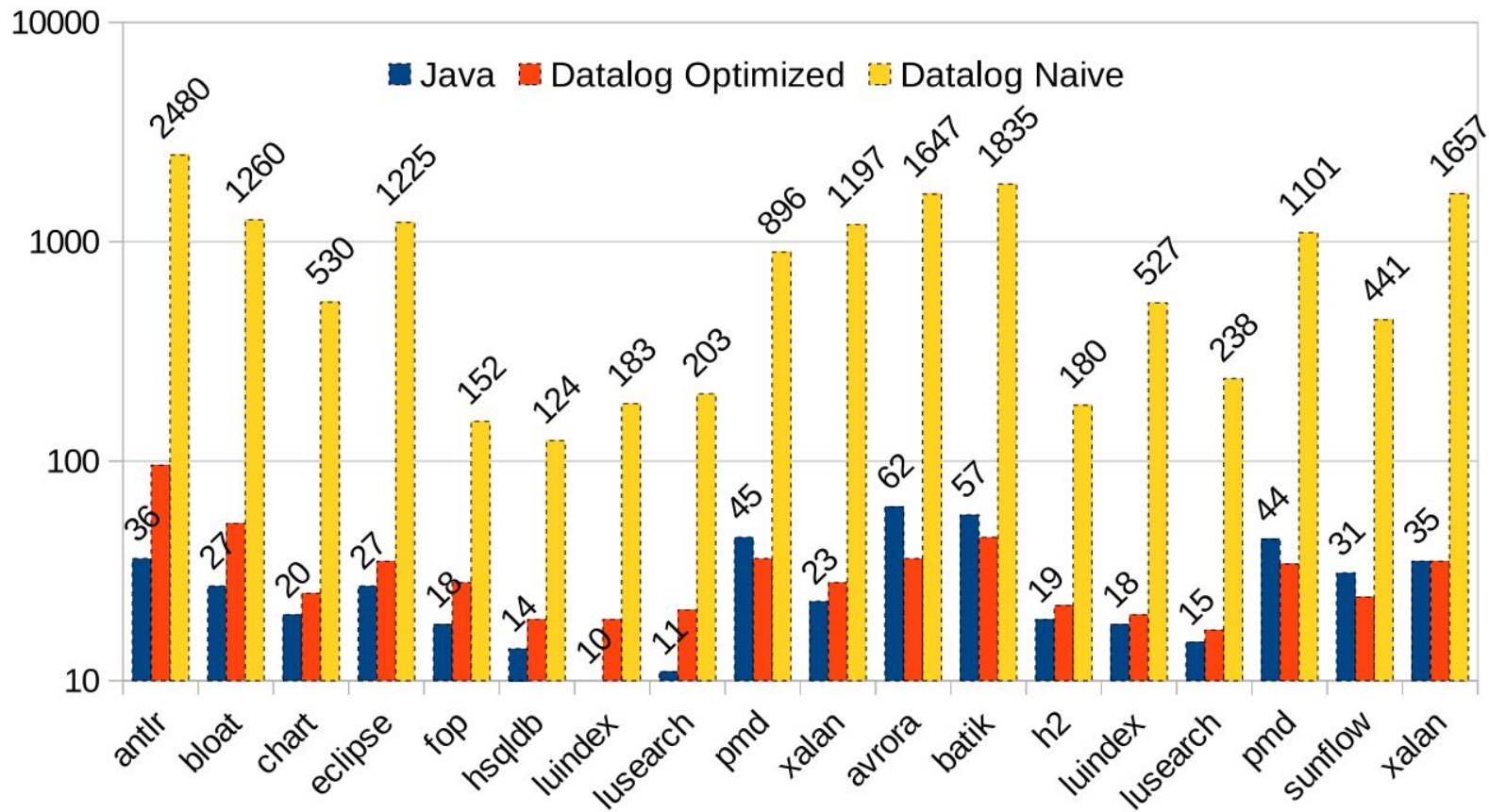




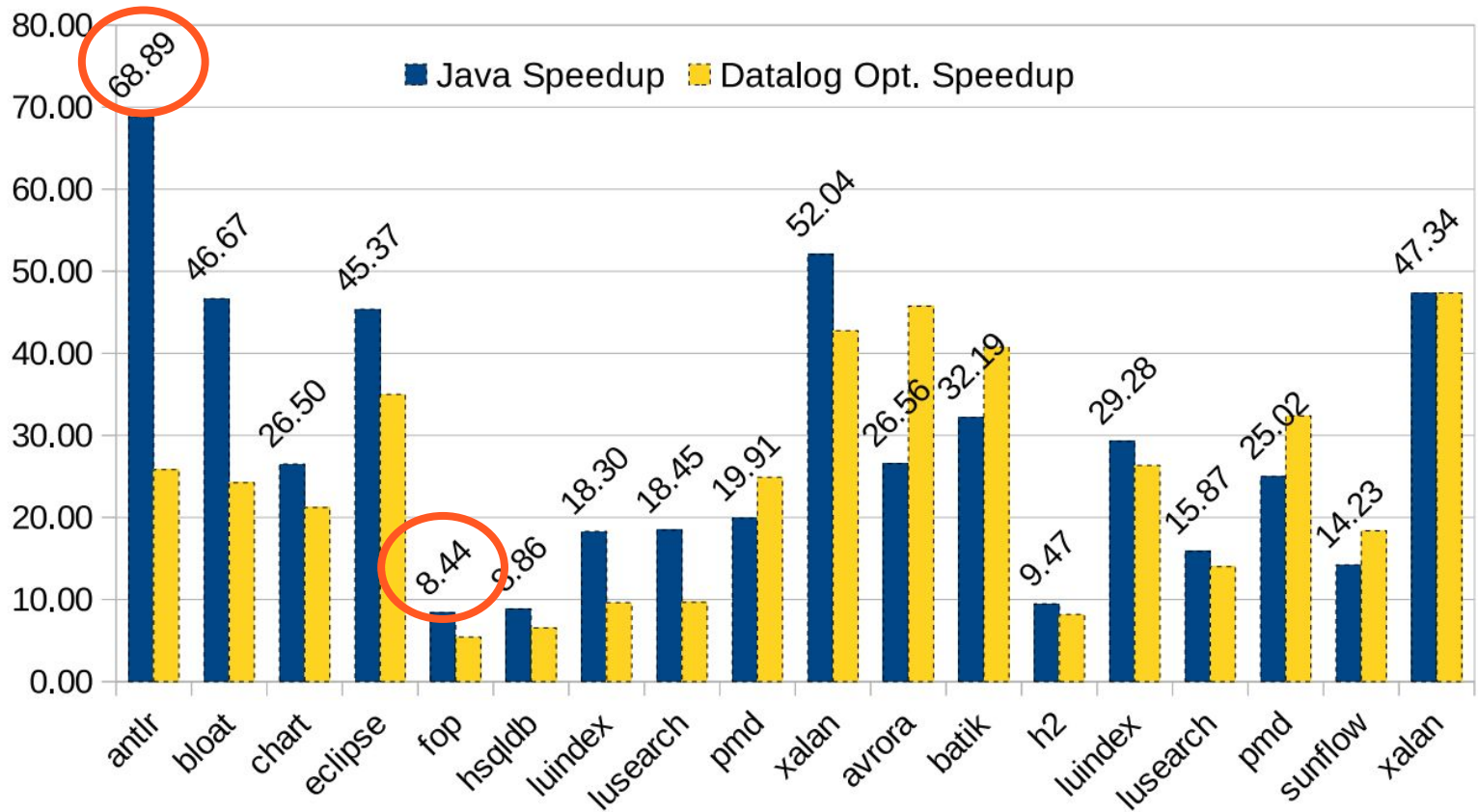
**Datalog Naive**

**Java**

**Datalog Opt**



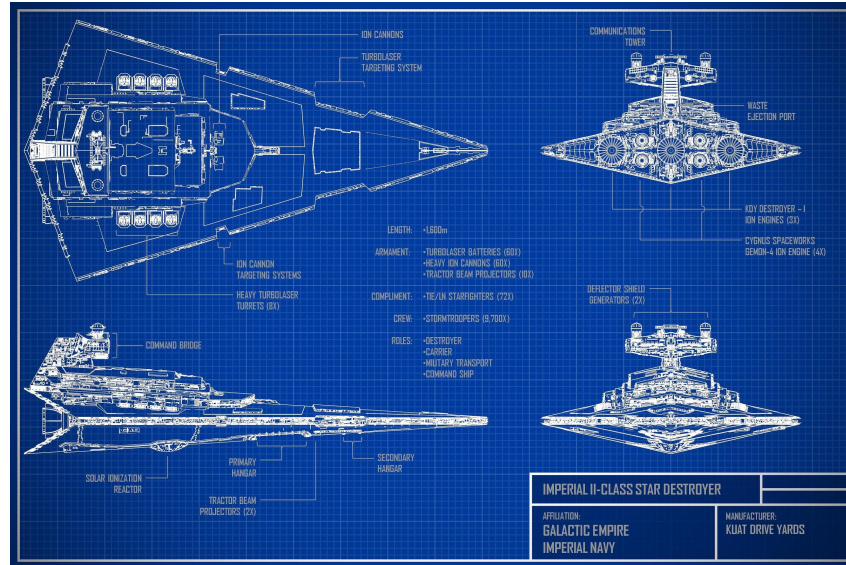
**Time**



**Speedup**

how?

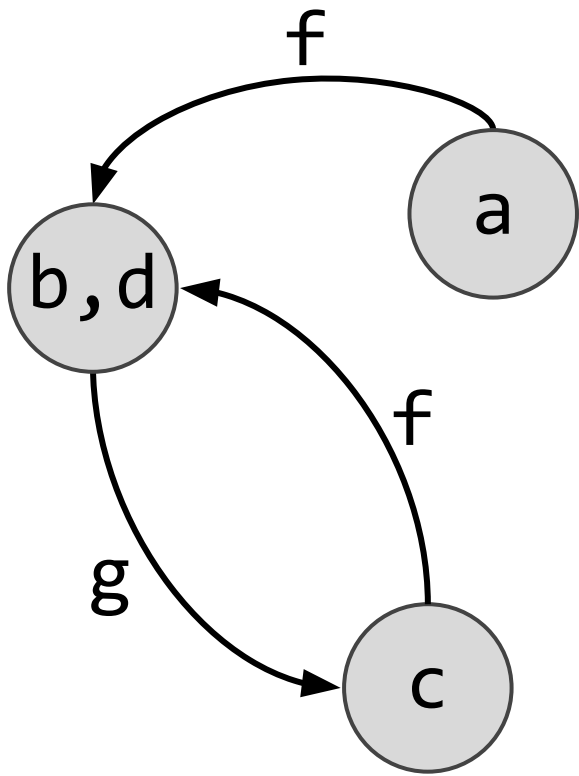
# an efficient data structure for Must-Alias Analysis



# Alias Graph

- *directed graph*
- *invent abstract objects (nodes) for what a variable points to*
- *edges represent fields*
- *access paths are paths in the graph*
- *paths to same node  $\rightarrow$  aliases*
- *merge aliasing variables*

- *one graph per (instruction x calling context)*
- *copy from one instruction to the next and apply semantics*
- *up until a fixpoint*



$b.g \sim c$

$d.g \sim c$

$a.f \sim b$

$c.f \sim b$

$a.f \sim c.f$

$a.f.g \sim c$

$a.f.g.f \sim b$

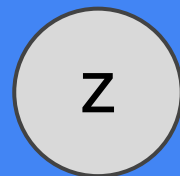
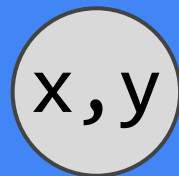
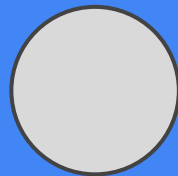
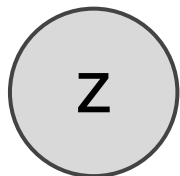
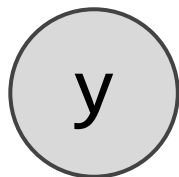
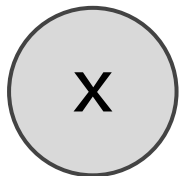
$a.f.g \sim b.f$

etc

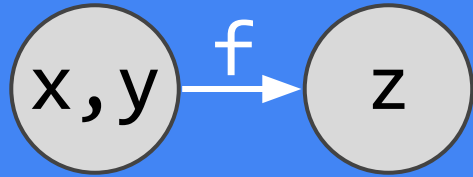
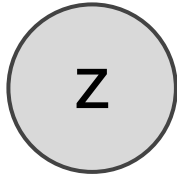
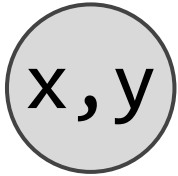


**Operations**

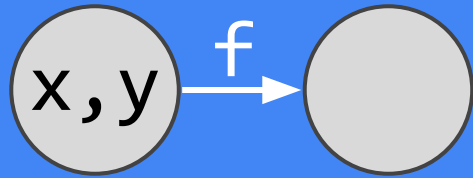
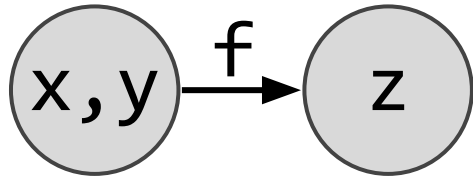
$$\mathbf{x} = \mathbf{y}$$



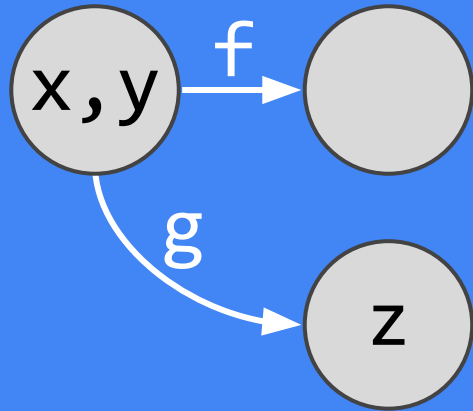
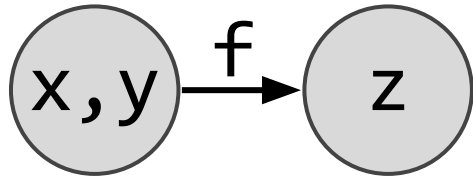
$$\mathbf{x.f = z}$$



$$z = y.g$$

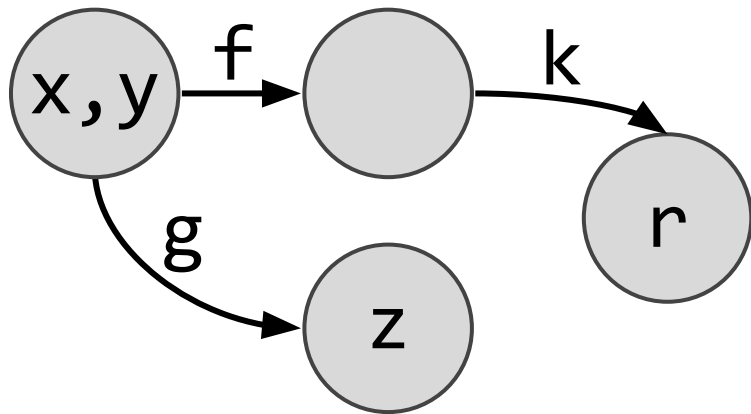


$$z = y.g$$

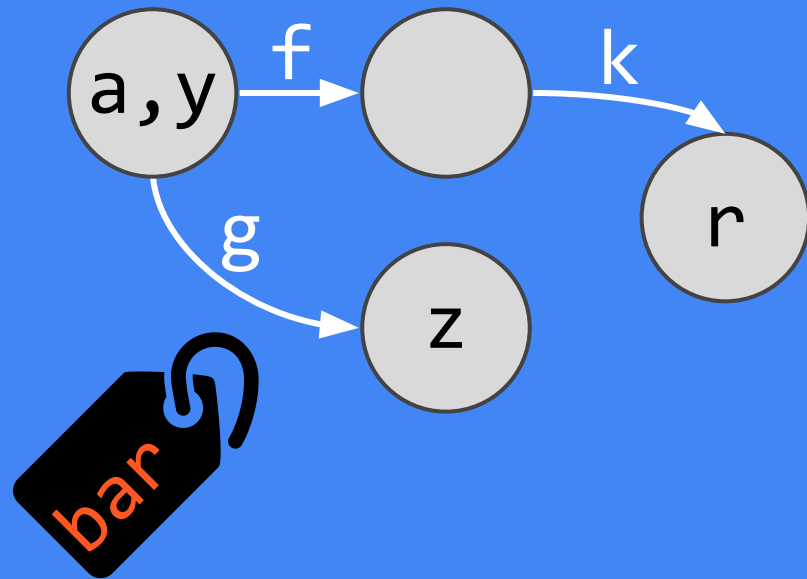


in method **bar**

**foo(x)**

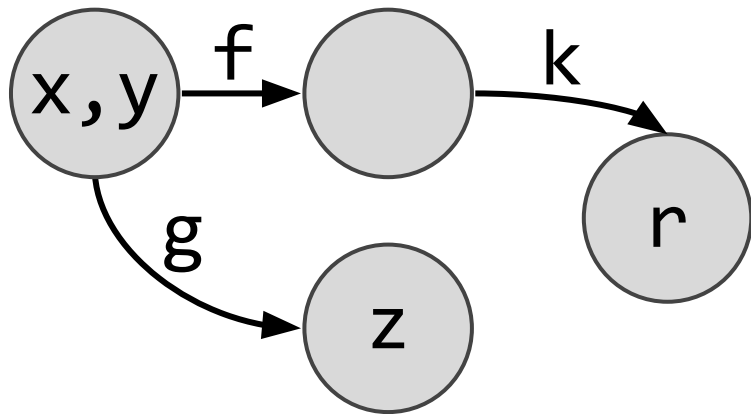


**foo(a) {**

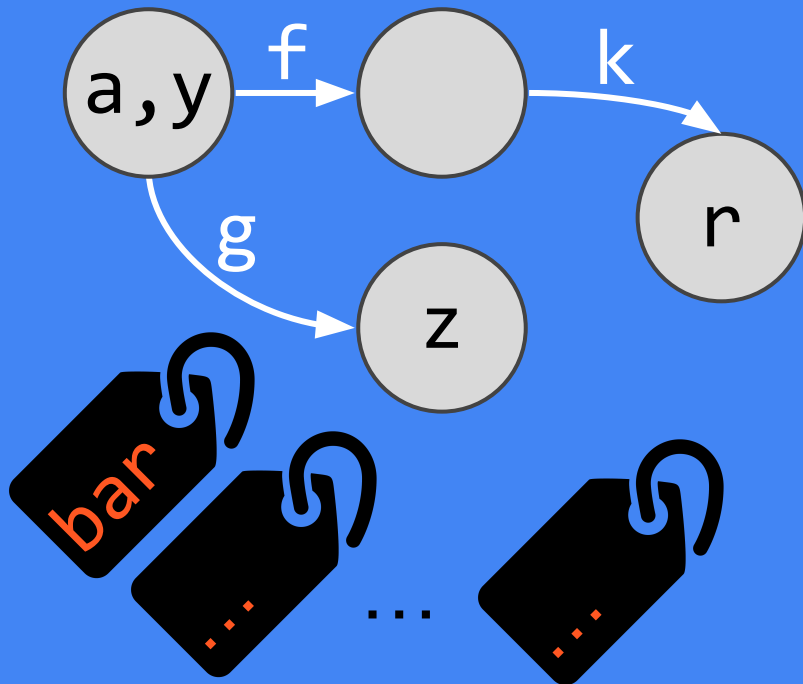


in method **bar**

**foo(x)**

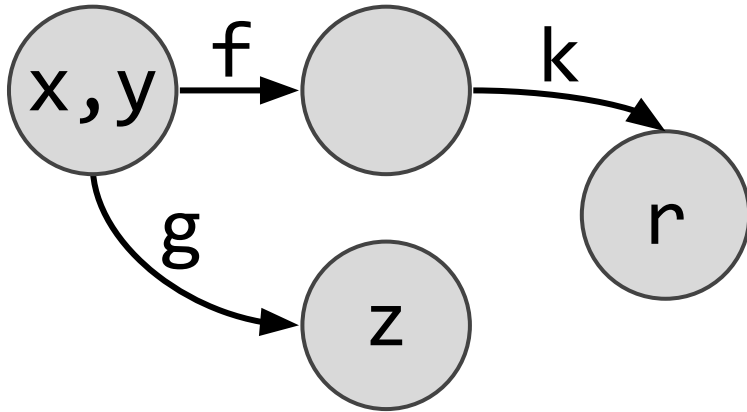


**T** `foo(a)` { ...

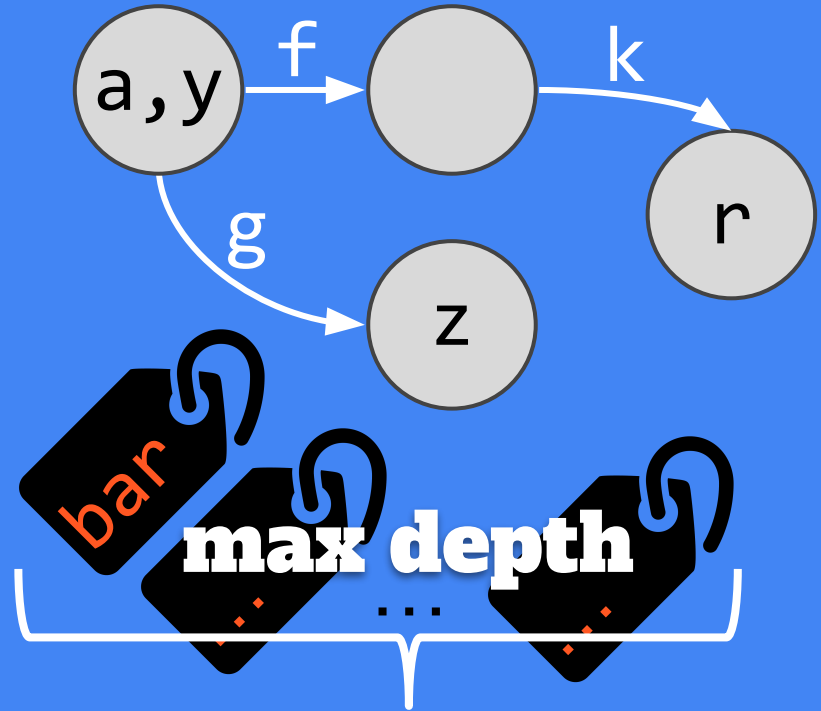


in method **bar**

**foo(x)**



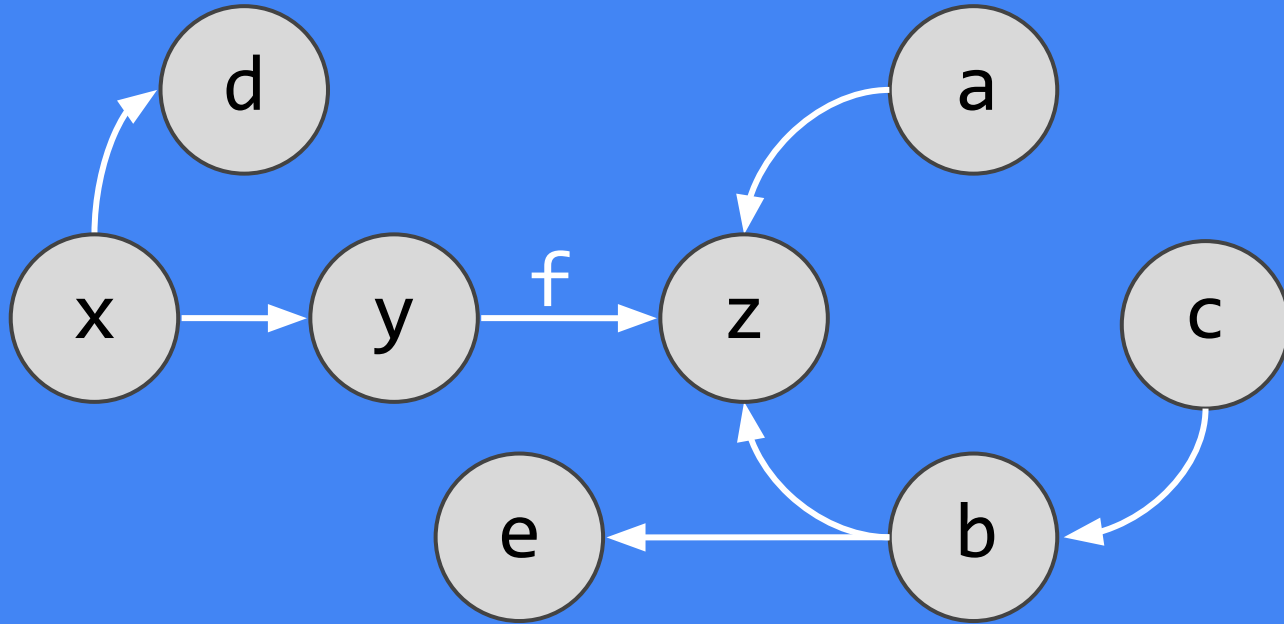
**T** `foo(a)` { ...



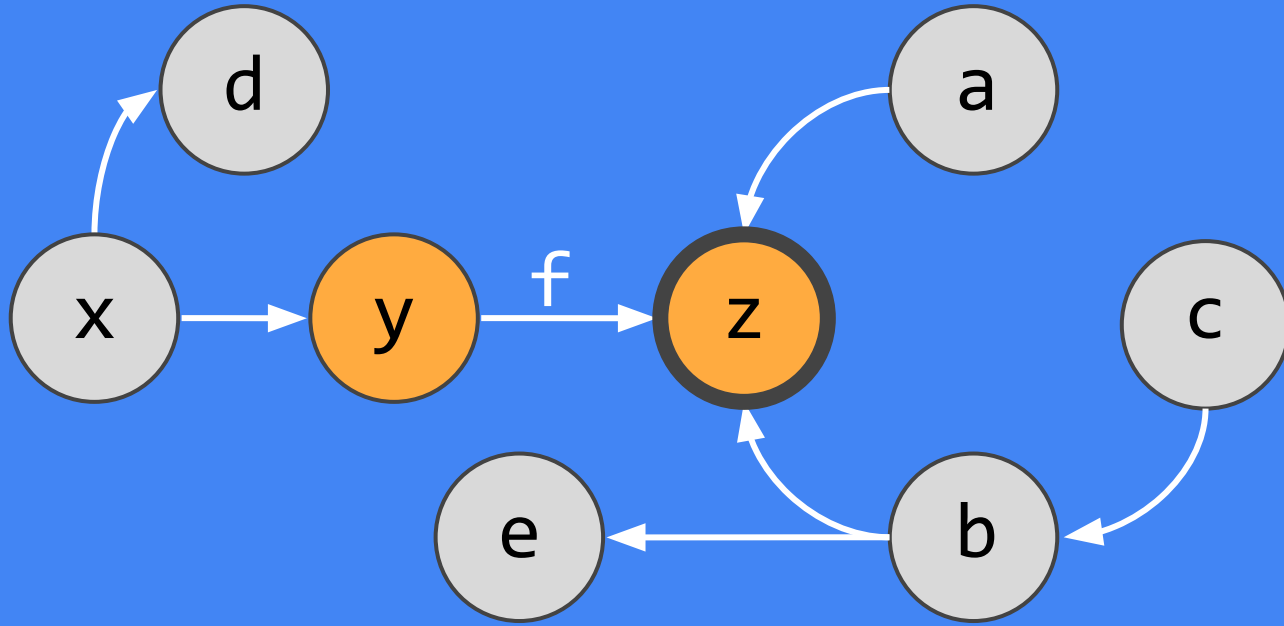


# Algorithms

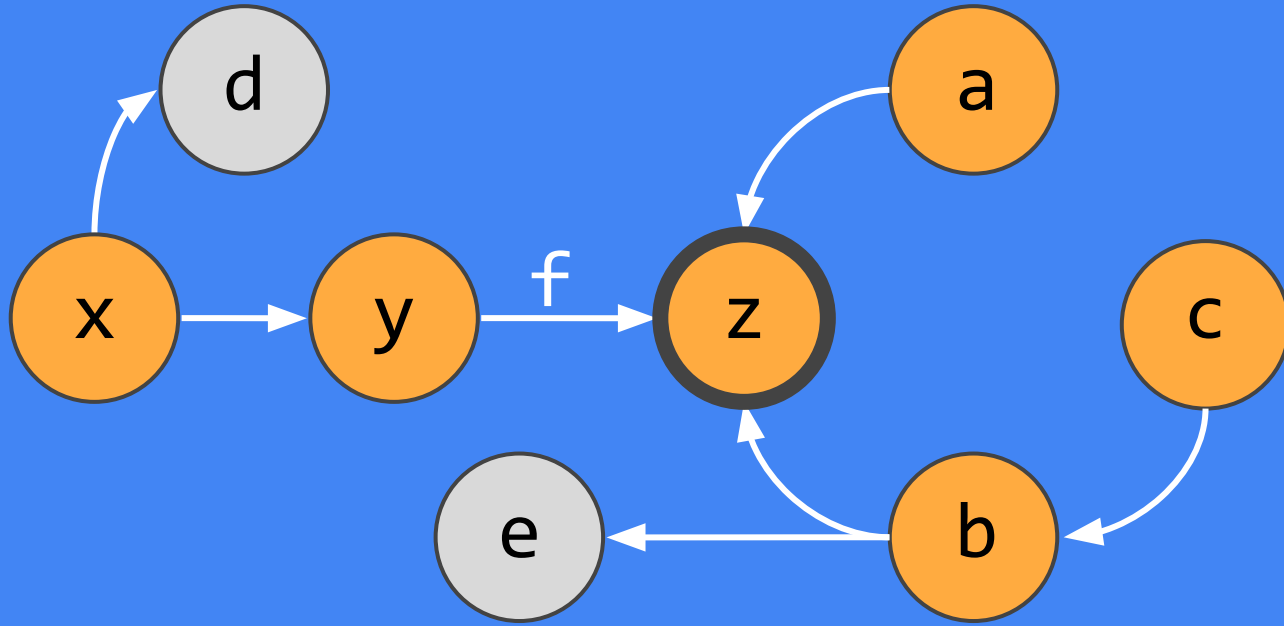
**allAliases(y.f, len)**



**allAliases(y.f, len)**

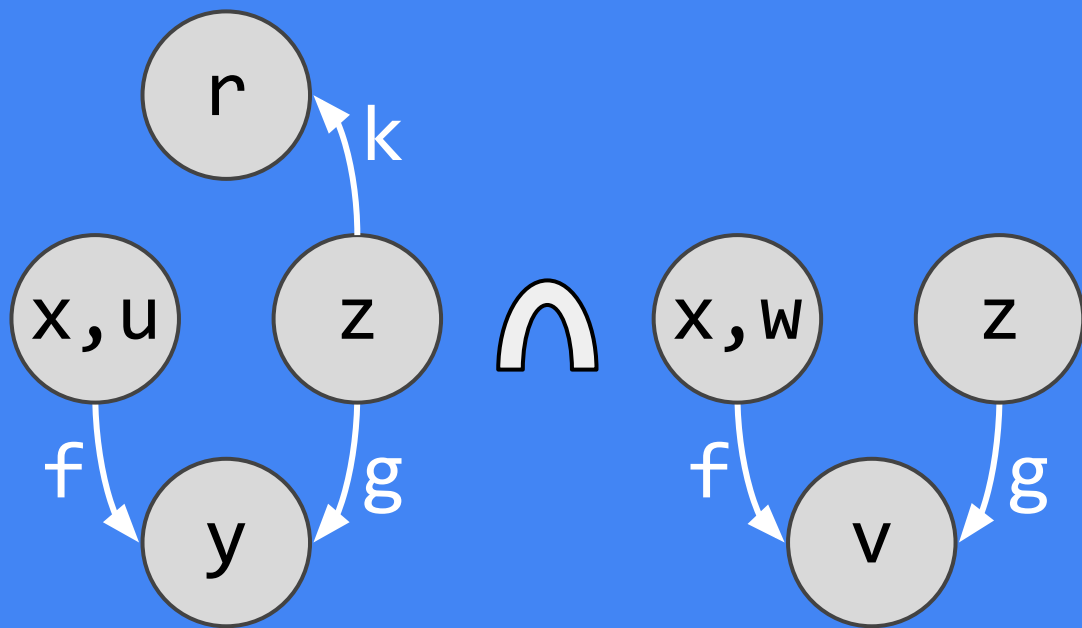


**allAliases(y.f, len)**

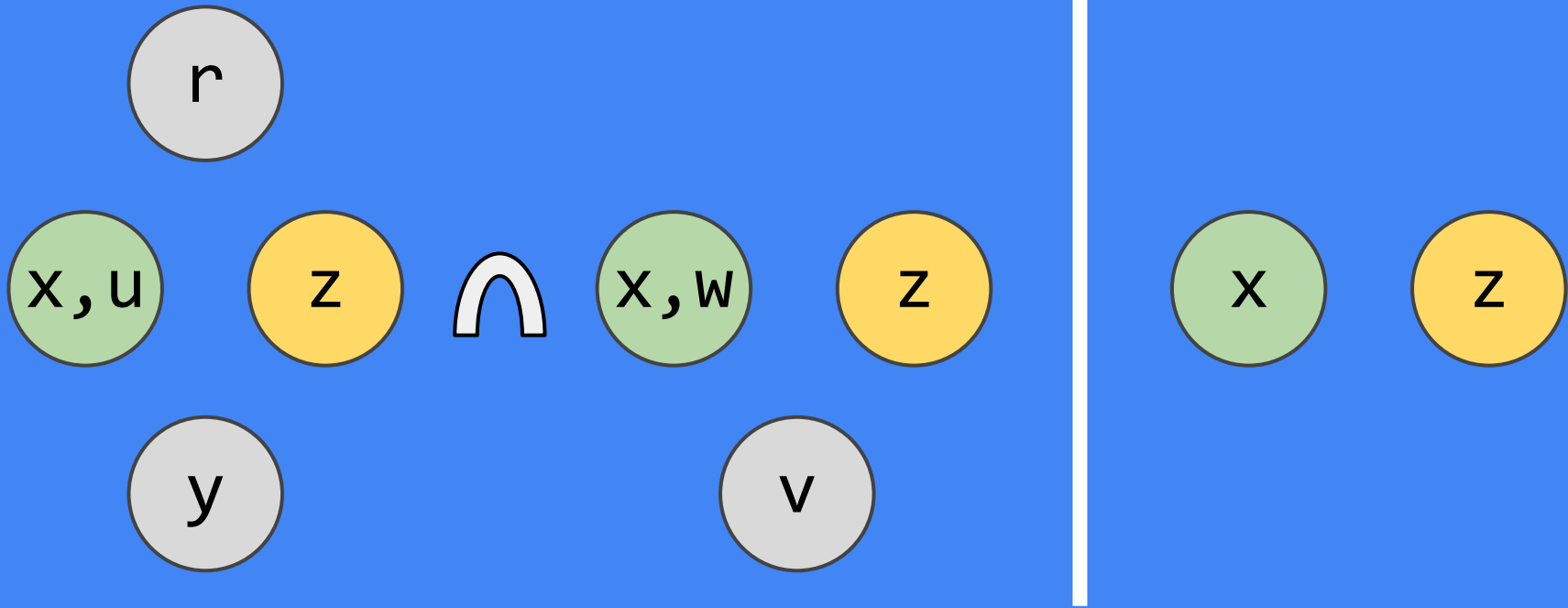


**allAliases(y.f, len)**

**intersect(g1, g2)**

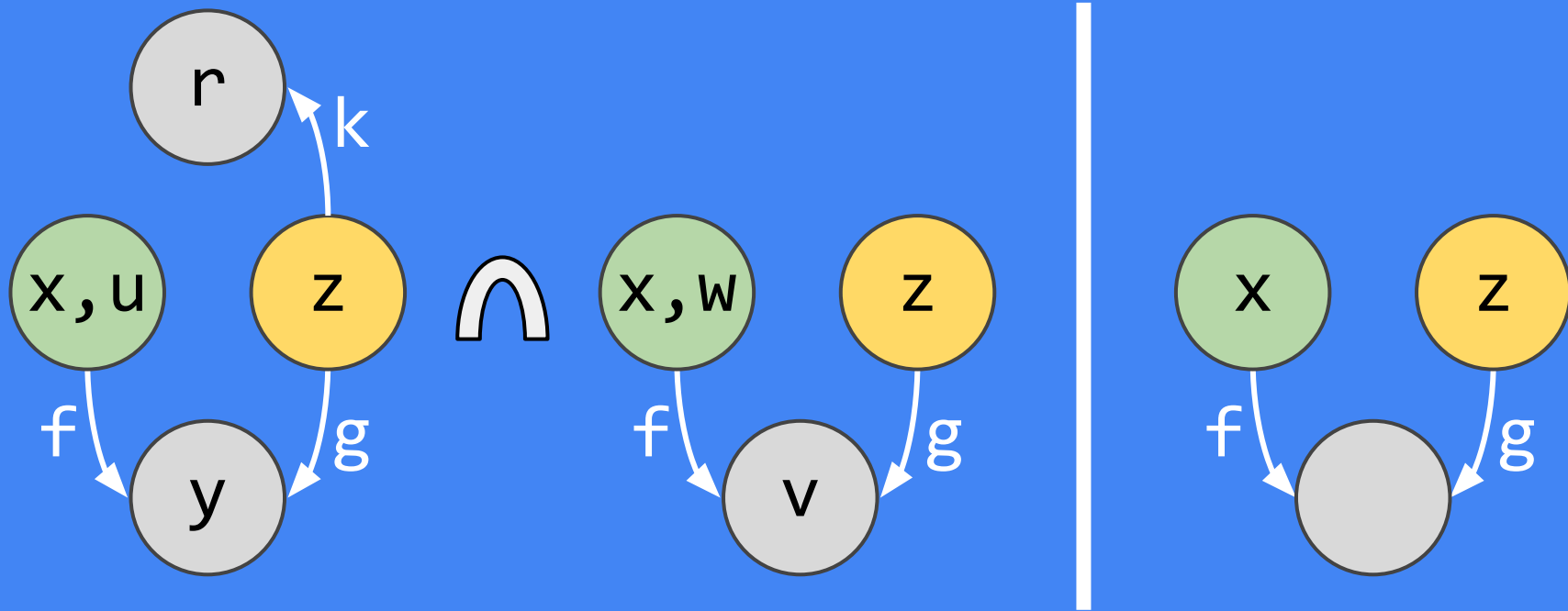


**intersect(g1, g2)**



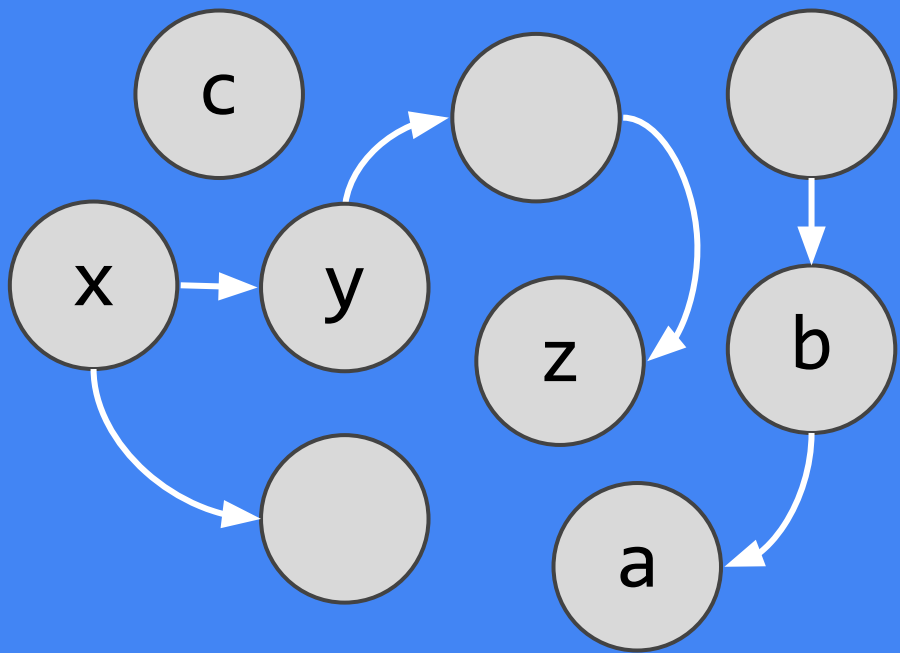
**intersect(g1, g2)**



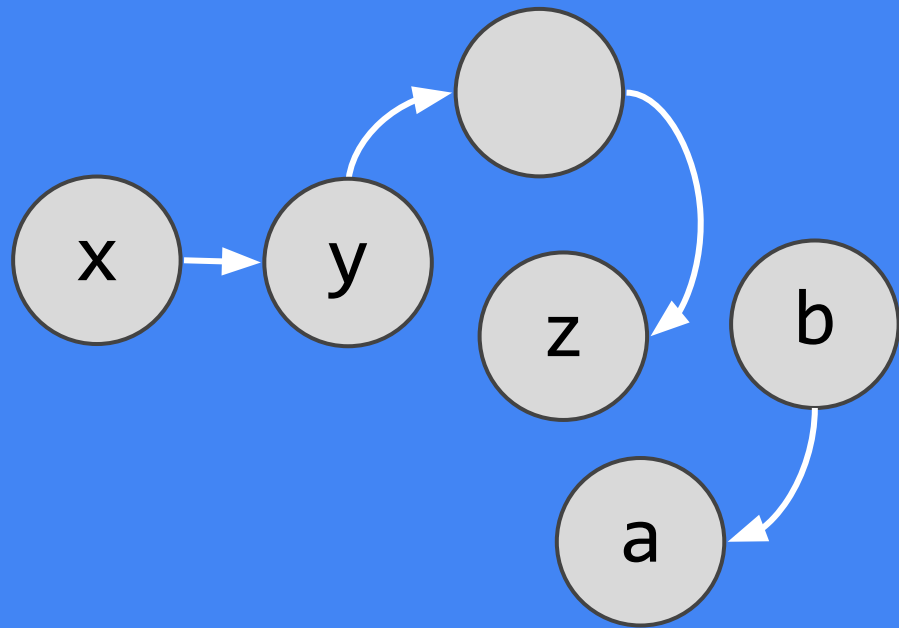
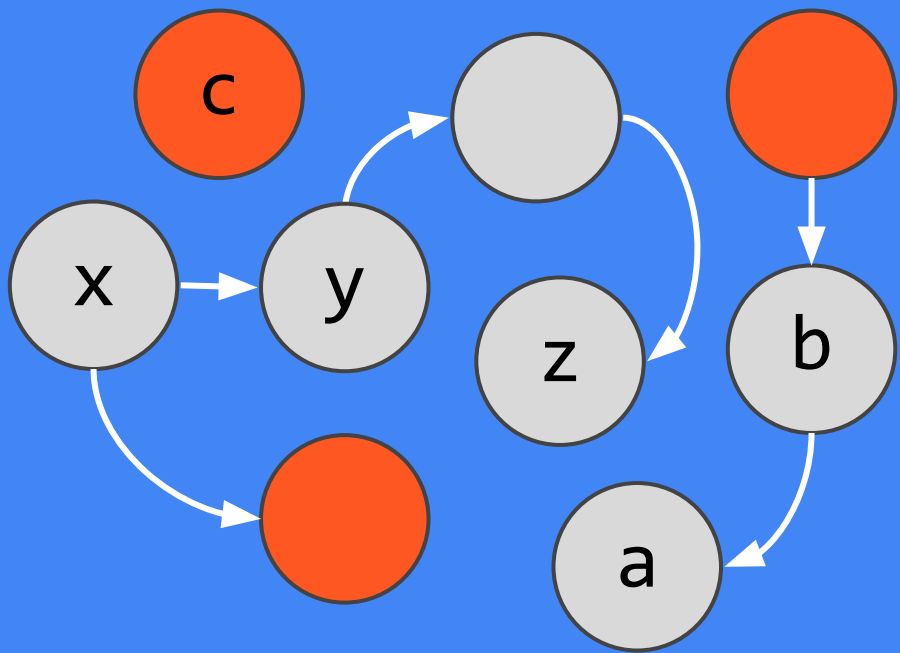


**intersect(g1, g2)**

**gc(g)**

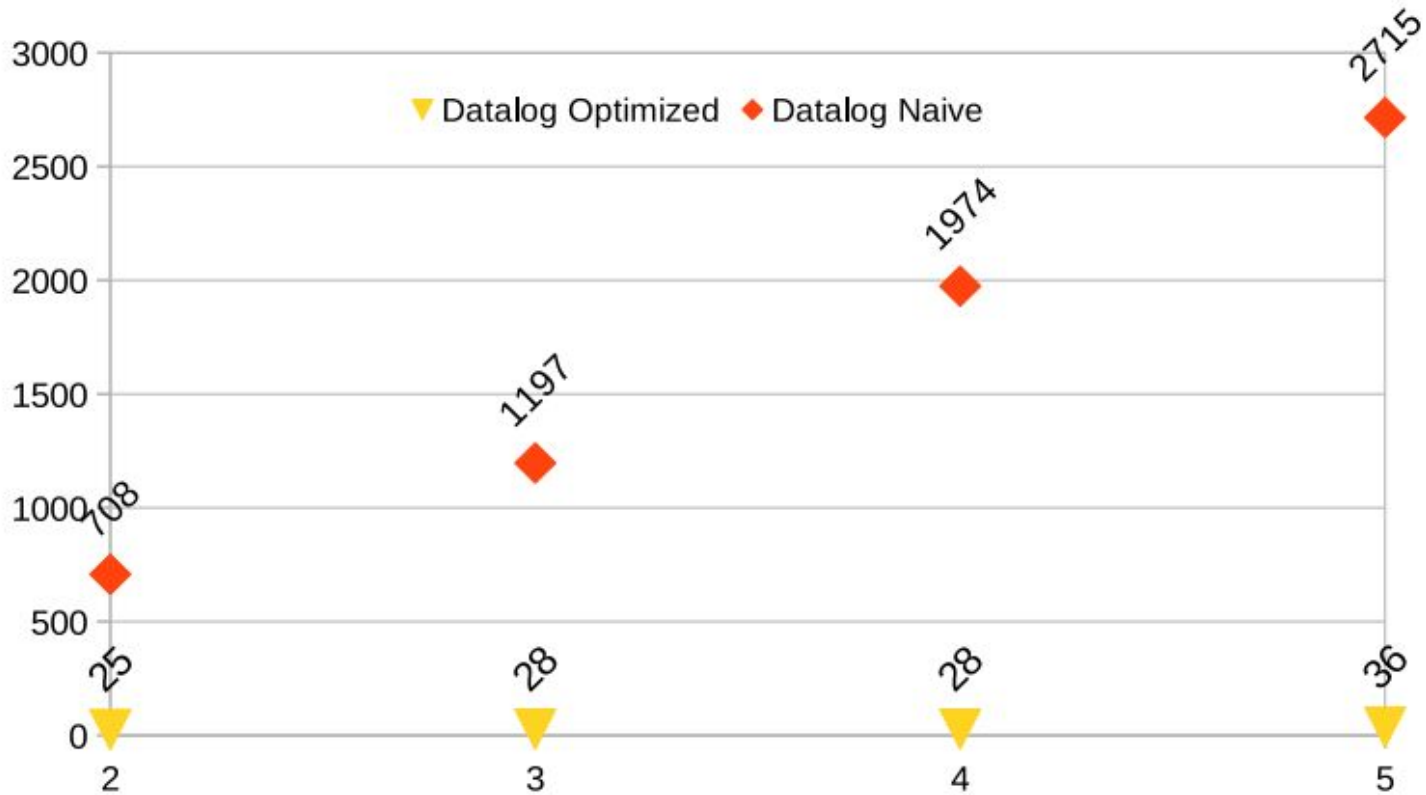


**gc(g)**

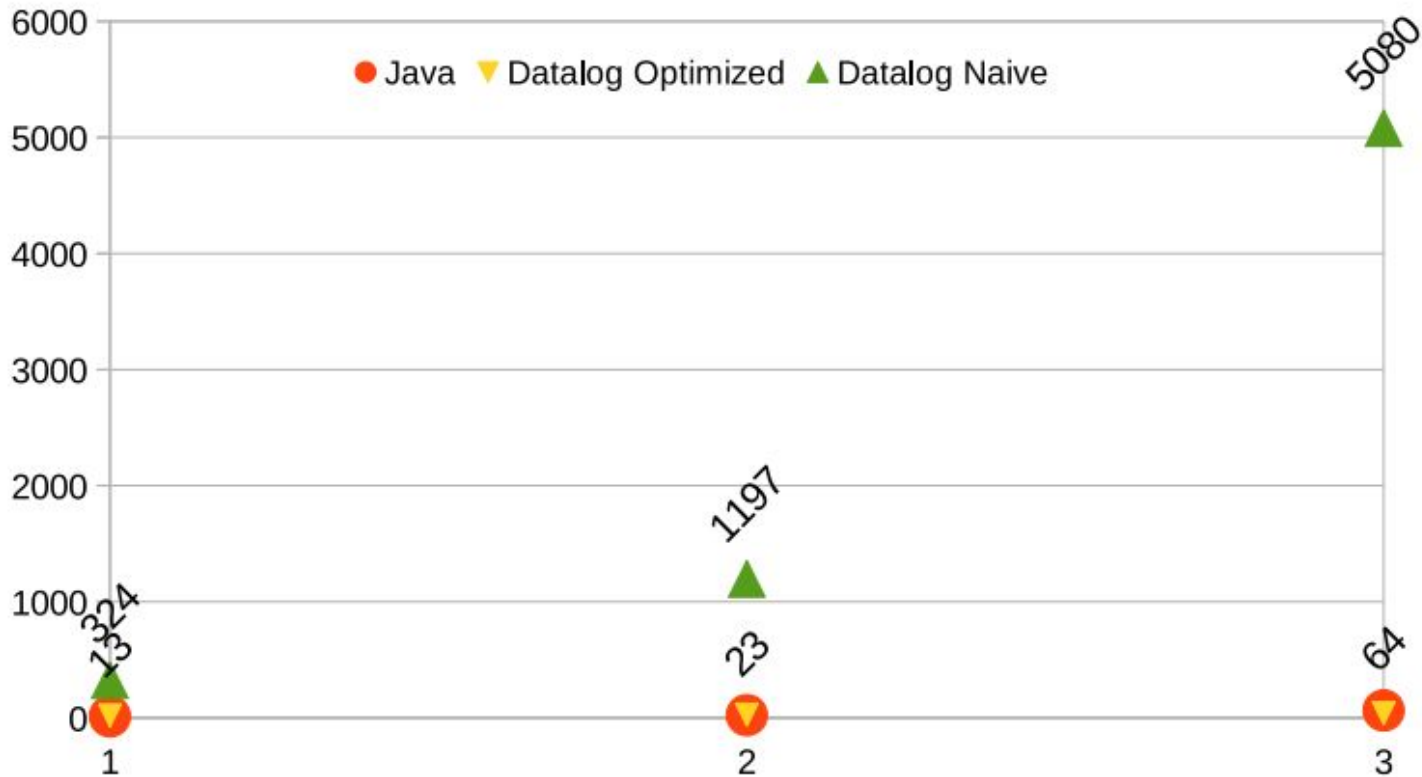


**gc(g)**





**Max Access Path Length x Time**



**Max Context Depth x Time**

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